

18V XR ROTARY LASER

DCE074D1R

Beam Colour	Red
Accuracy	+/-3mm @ 30m
Self-levelling Range	+/-5°
Max. Working Range With Detector	450m
Sloping Range	+/-10°
IP Rating	54
Tripod Connection	5/8"
Rotation Speed	150, 300, 600, 1200rpm
Laser Class	2
Modes	Vertical, Horizontal, Spot Only Up



18V XR ROTARY LASER

DCE079D1G

Beam Colour	Green
Accuracy	+/-1.5mm @ 30m
Self-levelling Range	+/-5°
Max. Working Range With Detector	600m
Sloping Range	+/-10°
IP Rating	67
Tripod Connection	5/8"
Rotation Speed	150, 300, 600, 1200rpm
Laser Class	2
Modes	Vertical only, Horizontal only, Spot Up & Down



10.8V XR CROSS LINE LASER

DCE088D1G

Beam Colour	Green
Accuracy	+/-3mm @ 10m
Self-levelling Range	+/-4°
Max. Working Range With Detector	50m
IP Rating	65
Number Of Beams	2 - Horizontal, Vertical
Tripod Connection	5/8", 1/4"
Pendulum Lock	Yes
Laser Class	2
Modes	Vertical Only, Horizontal Only, Cross Line



10.8V XR 3 X 360° CROSS LINE LASER

DCE089D1G

Beam Colour	Green
Accuracy	+/-3mm @ 10m
Self-levelling Range	+/-4°
Max. Working Range With Detector	50m
IP Rating	65
Number Of Beams	3 - Horizontal, Vertical, Side
Tripod Connection	1/4" x 5/8"
Pendulum Lock	Yes
Laser Class	2
Modes	360° Horizontal, 360° Vertical, 360° Vertical, 6x cross line plumb up & down



10.8V XR 5 SPOT CROSS LINE LASER

DCE0825D1G

Beam Colour	Green
Accuracy	+/-3mm @ 10m Spot +/-2 @ 10m
Self-levelling Range	+/-4°
Max. Working Range Line/Spot	30m/45m
IP Rating	65
Number Of Beams	7 - Cross Line plus 5 spots
Tripod Connection	1/4" x 5/8"
Pendulum Lock	Yes
Laser Class	2
Modes	Vertical Only, Horizontal Only, Cross Line, 3 Spot Only: Up, Down, Front, 5 Spot Only: Up, Down, Front, Both Sides



CROSS LINE LASER

DW088CG

Beam Colour	Green
Accuracy	+/-3mm @ 10m
Self-levelling Range	+/-4°
Max. Working Range with Detector	20-50m
IP Rating	54
Number Of Beams	2 - Horizontal, Vertical
Tripod Connection	1/4"
Laser Class	2
Modes	Vertical Only, Horizontal Only, Cross Line
Power Source	3 x AAA



DW088K - RED BEAM MAX. WORKING RANGE 15-50M WITH DETECTOR DW088KD - INCLUDES DETECTOR